

P1069

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B.E. (Electronics)

ADVANCED POWER ELECTRONICS

(2003 Course)

Time : 3 Hours]

[Max. Marks : 100

Instructions to the candidates:

- 1) Answer Q1 or Q2, Q3 or Q4, Q5 or Q6 from section I and Q7 or Q8, Q9 or Q10, Q11 or Q12 from section II.
- 2) Answers to the two sections should be written in separate books.
- 3) Neat diagrams must be drawn wherever necessary.
- 4) Figures to the right indicate full marks.
- 5) Use of logarithmic tables, slide rule, Mollier charts, electronic pocket calculator and steam tables is allowed.
- 6) Assume suitable data, if necessary.

SECTION - I

- Q1) a) Draw the circuit diagram of a three-phase semi-converter feeding a highly inductive (level) active load and the following waveforms for firing angle $\alpha = 60^\circ$:
- i) Supply phase voltages.
 - ii) Supply line voltages.
 - iii) Output voltage.
 - iv) Phase A line current. [8]
- b) A three-phase semi-converter operates from the 415V, 50Hz mains and feeds a highly inductive (level) active load having $R = 20\Omega$. If the firing angle is 60° , calculate: [10]
- i) Average (DC) load voltage.
 - ii) Average (DC) load current.
 - iii) RMS line current.

OR

- Q2) a)** With the help of a neat circuit diagram and relevant waveforms, explain the operation of a three-phase circulating-current type dual converter. Derive an expression for the peak circulating current in terms of the firing angle. [10]
- b)** A series-parallel bank of thyristors consists of 5 parallel strings, with each string containing 6 thyristors in series. The rating of all thyristors is identical with a voltage rating of 1600V and current rating of 1000A. During testing it was found that the maximum voltage withstand capability and maximum current carrying capacity of the bank was 8 KV and 4 KA, respectively. Calculate the series-string efficiency and parallel-string efficiency. [8]
- Q3) a)** With the help of a neat circuit diagram, relevant waveforms and mode equivalent circuits, explain the operation of a three-phase, 120° mode, voltage source inverter feeding a balanced, star-connected resistive load. Also derive an expression for the RMS phase output voltage and RMS SCR current. [10]
- b)** The above inverter operates from a 400V DC supply and feeds a balanced, star-connected resistive load of 25Ω per-phase. Calculate
- RMS phase output voltage.
 - RMS phase current.
 - RMS SCR current.
- [6]

OR

- Q4) a)** What are the different output voltage control and harmonic reduction techniques in inverters? Explain any one technique in detail. [10]
- b)** Cross-conduction ('shoot-through') faults are likely to occur in a 180° mode three-phase VSI but unlikely when the same inverter is operated in 120° mode. Justify.
- How would you modify the gate pulse waveforms of a 180° mode three-phase VSI so as to eliminate cross-conduction? [6]
- Q5) a)** With the help of a neat circuit diagram and relevant waveforms, explain the Symmetrical Angle Control (SAC) technique for power factor improvement in AC-DC converters. [8]

- b) Explain how the following parameters are sensed in power electronic circuits: [8]
- DC current.
 - AC current.

OR

- Q6) a) With the help of a power circuit diagram, control circuit block diagram and waveforms, explain the operation of a single-phase active wave-shaping circuit for power factor improvement. [10]
- b) Compare ZVS & ZCS converters. [6]

SECTION - II

- Q7) a) Compare servomotors with conventional DC motors and stepper motors. [8]
- b) With the help of a neat circuit diagram and relevant waveforms, explain the operation of an unipolar-voltage chopper drive for PM & hybrid stepper motors. [10]

OR

- Q8) a) With the help of a neat circuit diagram and relevant waveforms, explain the operation of a three-phase LCC based separately excited DC drive having a full converter in the armature circuit and a semi-converter in the field circuit. Also derive an expression for the motor speed in terms of armature converter firing angle, field converter firing angle, motor torque and supply voltage. [10]
- b) A 400V, 1500rpm, 15A separately excited DC motor with $R_a = 0.2\Omega$, $R_f = 225\Omega$, $K_v = 3.97/\pi$ V/A-rad/sec, is fed from a three-phase full converter operating from the 415V, 50Hz mains. The field circuit is fed from a three-phase semi-converter. Speed variation below base speed is obtained by armature voltage control with the field converter set at $V_f = 450V$, whereas speed variation above base speed is obtained by field voltage control with the armature converter set at $V_a = 450V$. Calculate.
- The armature converter firing angle for a motor speed of 900rpm if the motor torque is 30N/m.
 - The field converter firing angle for a motor speed of 1800rpm if the motor current is 10A. [8]

- Q9) a)** With the help of a neat circuit diagram and appropriate torque-speed curves, explain the slip power recovery scheme for speed control of induction motors in both sub-synchronous and super-synchronous speed regions. [8]
- b)** Explain the operation of a three-phase brushless DC motor drive with the help of a neat circuit diagram and relevant waveforms. [8]

OR

- Q10)a)** Explain the operation (any two) of the following motor protections:
- i) Field failure in DC motors.
 - ii) Soft start for DC motors.
 - iii) Phase failure for three-phase AC motors. [8]
- b)** A 6 pole, 380V, 60Hz, three-phase induction motor has a rated speed of 1160rpm. Calculate its speed, slip and slip frequency during electromagnetic braking under constant V/f control for a stator frequency of 45Hz, the braking torque (-ve) being equal to 75% of rated motor torque. [8]

- Q11)a)** What is meant by supply voltage waveform distortion in a power system? What are the causes and effects of harmonics and inter-harmonics in the power system? [8]
- b)** What are the different types of voltage transients present in a power system? List the mitigation techniques for these voltage transients. [8]

OR

- Q12)a)** Explain the terms 'Voltage sag (dip)' and 'Voltage swell (rise)'. What are the different sources / causes of voltage sags and swells? [8]
- b)** Explain how an Energy Audit helps in controlling energy losses in a typical production plant. [8]

