

T.E. (Comp.) (Semester – I) Examination, 2010 DIGITAL SIGNAL PROCESSING (2003 Course)

Time: 3 Hours Marks: 100

Instructions: 1) Answers to the two Sections should be written in separate books.

- 2) Neat diagrams must be drawn wherever necessary.
- 3) Use of logarithmic tables, slide rule, Mollier charts, electronic pocket calculator and steam tables is allowed.
- 4) Assume suitable data, if necessary.
- 5) Attempt Q. 1 or Q. 2, Q. 3 or Q. 4, Q. 5 or Q. 6 from Section I and Q. 7 or Q. 8, Q. 9 or Q. 10, Q. 11 or Q. 12 from Section II.

SECTION - I

 A) Explain the sampling process in ADC and discuss the problem of identical sampling.

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B) For a DT signal x(n) = 2[u(n) - u(n-4)], obtain following resulting DT signals:

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i)
$$x_1(n) = x(n-2) + \delta(n)$$

ii)
$$x_2(n) = x(\frac{n}{2})$$

iii)
$$x_3(n) = x(-n) + x(n+3)$$
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OR

2. A) State linearity and time invariant properties of a DT system and test it for a system –

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$$y(n) = x(n) - 2x(n-2)$$

B) Obtain a linear convolution of two DT signals -

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$$x(n) = h(n) = 1, -1 \le n \le +1$$



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- 3. A) Define ROC of Z-transform. Describe the ROC properties in detail.
 - B) Obtain inverse Z-transform using residue method where $X(Z) = \frac{Z}{(Z-1)^3}$.

OR

4. A) State and prove following properties of Fourier transform i) Periodicity ii) Time Reversal.

B) Obtain ZT of a given DT signal using ZT properties where – x(n) = 2nu(-n-1)Sketch the ROC.

- 5. A) Define system function H(Z). How it describes the properties of a DT system?

 What is pole zero plot? What do you mean by all pole and all zero system? 10
 - B) Determine the impulse response of a system described as y(n) + 3y(n-1) + 2y(n-2) = 2x(n) x(n-1).

OR

6. A) Obtain the frequency response of a system using simple geometric construction having impulse response – h(n) = {0.5, 0.5}. Obtain the difference equation of the system.

B) Draw a pole zero plot of a system described as – $y(n) = x(n) - x(n-1) + 0.2 \ y(n-1) + 0.15 \ y(n-2)$ what do you mean by multiple order poles/zeros?

SECTION - II

- A) Derive the first stage of DIF FFT algorithm. Draw the basic butterfly structure and obtain the computational complexity.
 - B) State and discuss the periodicity and symmetry property of N-point DFT. How can we compute N point circular convolution using DFT and IDFT?



8. A) Draw a signal flow graph for N = 8 for DIT FFT algorithm. Explain In-place computation and Bit-reversal indexing features of the algorithm. 10

- B) Obtain DT frequencies {W,} for 4-point DFT. For a DT sequence $x(n) = \{1, -2, 3\}$, obtain 4-point DFT using linear transformation matrix.
- 9. A) Define a DT filter. Prove that for an ideal frequency response, ∞ number of filter coefficients are required.

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B) Obtain corresponding DT filter using impulse invariance method from a CT filter having transfer function $H(s) = \frac{1}{s^2 + 3s + 2}$ with $F_s = 5$ sps.

OR

10. A) Write algorithmic steps to design an FIR filter using Hanning window. Compare Hanning with rectangular window.

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B) What is frequency warping effect in BLT method? Write down the design steps of BLT method for IIR filters.

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11. A) Draw a functional block diagram of ADSP 21XX processor and briefly explain DAG and MAC functional blocks.

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B) Explain linear phase FIR filter structure and draw it for filter length M = 5.

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OR

12. A) Obtain and realize direct and cascade form FIR filter structure for a system having -

$$h(n) = \{1, -3, 5, -3\}$$

B) Obtain and realize direct form – II IIR filter structure for a system

$$H(z) = \frac{z^2 + \frac{1}{3}z}{z^2 - \frac{3}{4}z + \frac{1}{8}}$$

What is the advantage of this form over Direct Form – I structure?

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