

P1352

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B.E. (Electronics)

ADVANCED POWER ELECTRONICS

(2003)

Time : 3 Hours]

[Max. Marks : 100

Instructions to the candidates:

- 1) Answer Q1 or Q2, Q3 or Q4, Q5 or Q6 from Section - I and Q7 or Q8, Q9 or Q10, Q11 or Q12 from Section - II.
- 2) Answers to the two sections should be written in separate books.
- 3) Neat diagrams must be drawn wherever necessary.
- 4) Figures to the right indicate full marks.
- 5) Use of logarithmic tables slide rule, Mollier charts, electronic pocket calculator and steam tables is allowed.
- 6) Assume suitable data, if necessary.

SECTION - I

Q1) a) Draw the circuit diagram of a three-phase fully-controlled converter feeding a highly inductive (level) active load and the following waveforms for firing angle $\alpha = 120^\circ$.

- i) Supply phase voltages.
- ii) Supply line voltages.
- iii) Output voltage.
- iv) Phase B line current.

[8]

b) A three-phase fully-controlled converter operates from the 415V, 50Hz mains and feeds a highly inductive (level) active load having $E = -400V$ and $R = 20\Omega$. If the firing angle is 120° , calculate :

- i) Average (DC) load voltage.
- ii) Average (DC) load current.
- iii) RMS line current.
- iv) Power supplied by the battery of the active load.
- v) Power fed back to the mains assuming the converter to be lossless.

[10]

P.T.O.

OR

- Q2) a)** Why are dual converters important? With the help of a neat circuit diagram and relevant waveforms, explain the operation of a three-phase dual mode dual converter. [10]
- b)** With the help of a neat circuit diagram, explain the technique for achieving equal voltage sharing of two series connected diodes. Derive the relationship between the current sharing resistors in terms of the diode parameters. [8]
- Q3) a)** With the help of a neat circuit diagram, relevant waveforms and mode equivalent circuits, explain the operation of a three-phase, 180° mode, voltage source inverter feeding a balanced, star-connected resistive load. Also derive an expressions for the following :
- i) RMS line-to-neutral output voltage.
- ii) RMS SCR' current. [10]
- b)** Explain the MMSR technique of selective harmonic elimination for inverters. [6]

OR

- Q4) a)** With the help of a neat circuit diagram, relevant waveforms and mode equivalent circuits, explain the operation of a three-phase, ASCSI feeding an induction motor load. [10]
- b)** Briefly explain any one technique for output voltage control and harmonic reduction in inverters. [6]
- Q5) a)** With the help of a neat circuit diagram and relevant waveforms, explain the Symmetrical Angle Control (SAC) technique for power factor improvement in AC-DC converters. [8]
- b)** Enumerate the different methods of sensing DC current in power electronic circuits and explain any one in detail. How would you modify this method to sense DC voltage? [8]

OR

- Q6) a) With the help of a neat circuit diagram, waveforms of capacitor voltage & inductor current and mode equivalent circuits, explain the operation of a ZVS resonant DC-DC converter. [10]
- b) What are the advantages of resonant converters over switched-mode converters? [6]

SECTION - II

- Q7) a) Compare the inherent properties of a typical DC stepper motor and DC servo motor with respect to any four of the following : [10]
- i) Speed control.
 - ii) Torque-speed behaviour.
 - iii) Shaft-torque and input power.
 - iv) Angular position control.
 - v) Rotor inertia.
 - vi) Start-stop operation at high speed.
- b) Explain half-stepping & micro-stepping modes of operation for stepper motors. [8]

OR

- Q8) a) With the help of a neat circuit diagram and relevant waveforms, explain the operation of a single-phase semiconverter-based separately excited DC motor drive. Derive expressions for the motor armature current and torque in terms of the firing angle, motor speed, field current and motor parameters. [12]
- b) A 230V, 1000rpm, 10A separately excited DC motor is fed from a single-phase semiconverter operating from the 230V, 50Hz mains. If $R_a = 0.75\Omega$, calculate the firing angle to obtain rated torque for a motor speed of 500rpm. [6]

Q9) Explain any two of the following methods for speed control of induction motors : [16]

- a) Variable frequency PWM-VSI drive.
- b) Stator voltage control.
- c) Slip power.

OR

Q10)a) With the help of the appropriate torque-speed characteristics, explain how electromagnetic braking is achieved for three-phase induction motors fed from a constant V/f variable voltage variable frequency drive. [8]

- b) A 4 pole, 415V, 50Hz, three-phase induction motor has a rated speed of 1460rpm. Calculate its speed, slip and slip frequency under constant V/f control for a stator frequency of 40Hz, the load torque being equal to 60% of rated motor torque. [8]

Q11)a) What are the different types of transients present in the power system? What are the sources of these transients? [8]

- b) What are the different types of industrial and residential/ commercial loads which contribute to harmonics in the power supply? Explain the effect of these harmonics on the working of power systems and connected equipment. [8]

OR

Q12)a) Write a short note on Energy Audit. [8]

- b) Enumerate the different types of short-duration power-line voltage disturbances and explain any two in detail. [8]

