

Total No. of Questions : 12]

SEAT No. :

**P1756**

**[4859]-114**

[Total No. of Pages : 2

**B.E. (Electronics)**

**EMBEDDED SYSTEMS**

**(Semester - I) (404203) (2008 Course)**

*Time : 3 Hours]*

*[Max. Marks : 100*

*Instructions to the candidates:*

- 1) Answer 3 questions from each section.*
- 2) Answers to the two sections should be written in separate books.*
- 3) Figures to the right indicate full marks.*
- 4) Assume suitable data, if necessary.*

**SECTION - I**

- Q1)** a) What are various software architectures used in embedded system design? [12]
- b) Describe the pico-net & scatter-net concept used in blue tooth protocol. [6]

OR

- Q2)** a) What are various design metrics used in embedded system design?[12]
- b) Describe the topologies supported in Zigbee protocol. [6]

OR

- Q4)** a) What are four major design rules used for RISC Processor? [10]
- b) Describe how interrupt latency can be minimized? [6]

- Q5)** a) With the help of data flow model of ARM processor, describe the load and store operation performed by the processor? [10]
- b) Compare ARM mode with Thumb mode. [6]

OR

**P.T.O.**

- Q6)** a) Describe Register banking concept used in ARM processor? [10]  
b) Describe the role of SPSR & CPSR in ARM processor. [6]

### **SECTION - II**

- Q7)** a) LPC 2148 is most suitable processor for protocol converter applications. Explain why? [6]  
b) Draw the interfacing diagram to interface  $8 \times 8$  keyboard matrix to LPC 2148 Processor. Also write C code for this interface? [10]

OR

- Q8)** a) Describe on chip ADC interface of LPC 2148. Also write C code for ADC operation? [8]  
b) Describe on chip PWM interface of LPC 2148. Also write C code for PWM operation? [8]

- Q9)** a) Traditional OS is not suitable for embedded system design. Explain why? [8]  
b) Describe state diagram of “ $\mu$ COS-II”. [8]

OR

- Q10)** a) What features of “ $\mu$ COS-II” makes it suitable for embedded system applications? [6]  
b) Describe various scheduling algorithms used in embedded system design. [10]

- Q11)** a) What are the techniques used in RTOS to handle inter task communication? [12]  
b) What are the techniques used in RTOS for the generation of the delay? [6]

OR

- Q12)** a) What are the reasons for priority inversion? How this problem can be solved? [8]  
b) Describe Cruise control system as an application of embedded system? [10]

