Total	l No.	o. of Questions : 12] SEAT No.	•
P4276		6 [4759] - 191A	l No. of Pages : 3
		B.E. (Information Technology)	
		EMBEDDED SYSTEMS	
		(2008 Pattern) (Elective - II)	
		Hours] [ions to the candidates:	Max. Marks : 100
	2) 3) 4)	Answer to the two sections should be written in separate answer In section I attempt: Q. No. 1 or Q. No. 2, Q. No. 3 or Q. No. 4, Q. In section II attempt: Q.No. 7 or Q. No. 8, Q. No. 9 or Q.No. 10, Q.N Neat diagrams must be drawn wherever necessary. Figures to the right indicate full marks. Assume suitable data, if necessary.	No. 5 or Q. No. 6.
		SECTION - I	
Q1)	a)	What are the advantages of using ASIC & SOC in embeding.	edded systems? [8]
	b)	Classify different embedded systems. List commicrocontrollers in each category.	mmonly used
		OR	
Q2)	a)) What are the embedded systems? How they are differe purpose systems?	nt than general [6]
	b)) What are the different components of an embedded syst	em? [6]

Q3) a) What are the different applications of timers in Embedded systems? How watchdog timer is different?[6]

c) Name the area of applications for the following processors:

Digital signal processor.

Media processor.

i)

ii)

b) Explain the techniques to optimize the use of power in an embedded system? [6]

c) What are the types of memory that can be used in an embedded system? Justify their used. [6]

OR

[4]

Q4)	a)	How a designer selects EPROM, RAM and peripherals required for adaptive cruise control system? Explain.	an 8]
	b)	Explain the process of converting a C program into a file for ROM image	
	c)	Explain in brief the use of following in an embedded system: i) Real time clock	6]
		ii) UART	
Q5)	a)	List and describe five types of device driver functions.	8]
	b)	Name features of RS-232C. Explain the RS-232C signals used to communication.	or [8]
		OR	
<i>Q6</i>)	a)	Explain different features of CAN protocol.	8]
	b)		in [8]
		SECTION - II	
Q7)	a)	Explain the advantages of programming embedded systems usi high-level languages.	ng [8]
	b)		18. [6]
	c)	When do you use assembly language for embedded system programmin	g? [4]
		OR	
Q8)	a)	Compare Java and C++ programming and their suitability for embedd systems.	ed [6]
	b)		ve [6]
	c)	What is in-circuit emulator? Give details of its use in embedded syste development.	em [6]
Q9)	a)	When do you require RTOS?	[6]
	b)	With the help of neat diagram, explain cooperative round robin scheduli model for RTOS. What is interrupt latency time for this scheduling mod [1]	_
		$\bigcap \mathbb{D}$	

Q10)	a)	With the help of neat diagram, explain preemptive scheduling for RTO:	S. 8]
	b)	How can you manage without RTOS? [8	8]
Q 11)	a)	Differentiate MicroC/OS-II and Vx Works based on features and the area of application.	eir 6]
	b)	With the help of neat system block diagram, explain the system requirements and tasks for an adaptive cruise control system in a car. [10]	
		OR	
Q12)	a)	How tasks are managed in MicroC/OS-II? Explain in detail. [8	8]
	b)	With help of neat diagram, explain synchronization of tasks and IPCs for TCP/IP network application.	or 8]

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