Total No. of Questions : 8]	SEAT No.:

P4733 [Total No. of Pages : 2

## [4760]-1071

## M.E. (Mechanical) (Design Engineering)

MECHANICAL MEASUREMENT AND CONTROL (2013 Pattern) (Semester - III) Time: 3 Hours [Max. Marks: 50 Instructions to the candidates: Answer any Five questions. 1) 2) Neat diagrams must be drawn wherever necessary. Figures to the right side indicate full marks. 3) Use of calculator is allowed. 4) 5) Assume suitable data, if necessary. a) Explain different types of errors in measurement. [5] *Q1*) b) Explain uncertainty in measurement system. [5] a) Computer Karl Pearson coefficient of correlation from the following O2)data using 20 as mean for price, 70 as mean for demand. [6] Price 14 16 17 18 19 20 21 22 |Demand | 84 78 70 75 66 67 58 62 60 b) Differentiate between regression and correlation analysis. [4] a) Computer correlation coefficient from the data O3)[7]  $N = 10 \sum x = 350; \sum y = 310m, \sum (x - 32)^2 = 162, \sum (y - 32)^2 = 222,$  $\sum (x-35)(y-31) = 92$ b) What are the properties of regression coefficients. [3] a) Explain the construction and working of ultrasonic flow meter. (Q4)[6]

b) Explain the working of thermal conductivity gauge with a neat sketch. [4]

a) Explain with neat sketch, principle of working of capacitance level gauge. Q5)[6]

b) How do you measure frequency and phase angle? [4]

- **Q6)** a) Differentiate between time domain and frequency domain based modelling approach. [5]
  - b) Discuss the application of closed loop control system in automotive. [5]
- Q7) a) Using Routh Horwitz criterion, find the stability of closed loop system given below

$$C(s)/R(s) = (2s+1)/(s^3+3s^2+3s+1)$$
 [7]

- b) Discuss the importance of Transient response specifications w.r.t. performance of control system. [3]
- **Q8)** a) Discuss the advantages of PID controller. [5]
  - b) Explain frequency domain analysis using Bode plots. [5]

