Total No.	of Question	s:12
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SEAT	No. :		
	Total	No. of Pages	:3

P3436

[4959]-211

B.E. (Computer Engineering)c: EMBEDDED SYSTEMS

(2008 Course) (Elective - II) (Semester - I) (410445)

Time: 3 Hours] [Max. Marks:100

Instructions to the candidates:

- 1) Answer Question No. 1 or 2, 3 or 4, and 5 or 6 from section I and Q.No. 7 or 8, 9 or 10 and 11 or 12 from section II.
- 2) Answers to the two sections must be written in separate answer books.
- 3) Neat diagrams must be drawn wherever necessary.
- 4) Figures to the right indicate full marks.
- 5) Assume suitable data, if necessary.

SECTION-I

- Q1) a) What are the different categories of Embedded Systems depending on the area of applications? Give Examples.[8]
 - b) Discuss various application areas of embedded system. [4]
 - c) Explain how embedded processor and Application Specific system Processors are different than a general processor? [6]

OR

- **Q2)** a) Differentiate between RISC and CISC architecture of the processors used in embedded systems. [6]
 - b) What challenges are faced while designing an embedded system. [6]
 - c) Draw layered architecture of Embedded system. Discuss various components in the Embedded System. [6]
- **Q3)** a) Draw the architecture of ARM7 core. How ARM9 family is different than ARM7? [8]
 - b) Discuss different structural units in a processor in an embedded system. Mention few advanced units. [8]

OR

Q4)	a)	Which parameters are dependent on supply voltage and clock freque in a system?		ncy [4]
	b)	Describe different operating modes of ARM7 processor.		[6]
	c)	It is required to design a real time robotic control system. For this application, select the appropriate processor based on [6]		
		i)	Instruction cycle time	
		ii)	Bus width	
		iii)	MIPS	
		iv)	On chip cache	
		v)	On chip RAM/ROM	
Q5)	a)	Con	npare RS232 and RS485 standards.	[4]
	b)	Disc	cuss 12C protocol w.r.t. following points	[8]
		i)	Data transfer speed	
		ii)	Arbitration	
		iii)	Data frame format	
	c)	Whi	ch optical devices are commonly used in embedded systems?	[4]
			OR	
Q6)	a)		cuss different field in the data frame of CAN bus protocol. What applications of CAN?	are [8]
	b)		cuss the topology used by devices to communicate through U ocol. Mention different types of data transfer.	ISB [8]
			SECTION-II	
Q7)	a)		at are the advantages and disadvantages of programming in C++ pedded system?	for [8]
	b)	Wha	at is In-circuit-Emulator? Give details.	[6]
	c)	Hov	v cross compilers are different than compilers?	[4]
			OR	

Q8)	a)	Exp	lain the use of data structures namely stack and tree in brief.	[6]
	b)		v java is useful in embedded system programming? Also mention dvantages.	its [6]
	c)	Exp imag	alin the process of converting a C program into a file for RC ge.)M [6]
Q9)	a)	Exp	lain the kernel services in an OS.	[8]
	b)	Hov	v RTOS performs the schedule management of multiple tasks.	[8]
			OR	
Q10,) a)		cuss different ways in which interrupts are handled in RTG ronment.	OS [6]
	b)	Wha	at are virtual device drivers? Explain.	[6]
	c)	Diff	erentiate between RTOS and embedded OS.	[4]
Q 11,) a)	Exp	lain digital camera with respect to hardware and software componer	nts. [8]
	b)		Perentiate between soft real time operating system and hard real time ating system.	me [4]
	c)	Identify the requirements of s/w mobile phone and show it with the hel of class diagram. [4]		elp [4]
			OR	
Q12) a)	Disc	cuss different features of µCOS-II.	[4]
	b)	Differentiate between Embedded OS and Desktop OS.		[4]
c)		Writ	te short note on any two	[8]
		i)	Embedded Linux.	
		ii)	VxWorks.	
		iii)	Special OS features for automotive systems.	