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[4959]-1142 B.E.(I T)

REAL TIME & EMBEDDED SYSTEMS (2012 Course) (Semester-II)(End Sem)(Elective-IV)(414464B) Time: 2½ Hours IMax. Marks: 70 Instructions to the candidates: Answer Q1 or Q2,Q3or Q4, Q5 or Q6, Q7 or Q8, Q9 or Q10. 2) Neat diagrams must be drawn wherever necessary. 3) Figures to the right side indicate full marks. Assume suitable data if necessary. Discuss the advntages and disadvantages of top-down and bottom-up **Q1)** a) design process in embedded system design. Explain Myrinet with suitable Myrinet network diagram. b) [4] Draw & explain general architecture of embedded system & explain **Q2)** a) components in it. [6] What are main features of CAN2.0 bus standards b) [4] *Q3*) a) List the key features of SHARC processor and discuss the targeted application areas for this processor. [6] Explain the structure of 12C bus, Draw state transition diagram for 12C b) bus master. [4] OR Discuss various modes of operation of ARM processor with respect to *Q4*) a) their operational usability. b) Calculate a message delay for 12C bus operating at 400 kilobits per second. The data size of the message is 14 bytes. [4] Use RMS scheduler for scheduling a periodic task set of T1(2, 4)& **Q5)** a)

- T2(4, 8). Perform schedulability check & comment on whether given task set is schedulable & schedule produced is feasible. [10]
 - b) Give the classification of the scheduling algorithms, compare and contrast static vs.dynamic algorithms with examples. [8]

- **Q6)** a) Use EDF scheduler for scheduling a periodic task set of T1(1, 3, 3)&T2 (4,6,6). Perform schedulability check & comment on whether given task set is schedulable & schedule produced is feasible. [10]
 - b) Give the structure of cyclic scheduler. Discuss the advantages and disadvantages of cyclic scheduler. [8]
- Q7) a) State & explain prority inversion problem with appropriate example & name protocols used to remove this problem.[8]
 - b) What is resource reclaiming? State needs of resource reclaiming algorithm. [8]

OR

- **Q8)** a) With appropriate example prove that priority ceiling protocol avoids deadlock. [8]
 - b) State algorithms for combined scheduling of periodic & aperiodic tasks& Compare them.[8]
- **Q9)** a) State & explain features & characteristics of Real time operating system (RTOS). [8]
 - b) Explain in detail any one commercial RTOS. [8]

OR

- Q10) a) State & explain, features & characteristics of Real Time Databases. [8]
 - b) Explain in detail any one commerical Real Time Database. [8]

