Total No.	of Questions	:	12]
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SEAT No. :	
SEAT NO.	

P1666

[5058]-154

[Total No. of Pages: 4

T.E. (Computer)

DIGITAL SIGNAL PROCESSING

(2008 Course) (Semester - I)

Time: 3 Hours

[Max. Marks : 100]

Instructions to the candidates:

- 1) Answers to the two sections should be written in separate answer-books.
- 2) Answer any three questions from each section.
- 3) Neat diagrams must be drawn wherever necessary.
- 4) Figures to the right side indicate full marks.
- 5) Use of Calculator is allowed.
- 6) Assume Suitable data, if necessary.

SECTION - I

Q1) a) Define and calculate nyquist rate for an analog signal, [6]

 $x_a(t) = 3\cos 50\pi t + 10\sin 300\pi t - \cos 100\pi t$.

b) Define linear convolution. Explain different properties of convolution with example. [10]

OR

Q2) a) Obtain a linear convolution of DT signal

[8]

$$x(n) = h(n) = \{1, 2, -1\}.$$

- b) State static, dynamic system properties of a DT system and test it for
 - i) y(n) = x(2n)
 - ii) $y(n) = x^2(n)$

[8]

Q3) a) Find the Fourier transform of the following:

[8]

- i) $\partial (n-1) + \partial (n+1)$
- ii) $\partial (n+2) \partial (n-2)$
- b) Compare DFT with DTFT. State and prove linearity property of DFT.[8]

OR

- **Q4)** a) Obtain 2-point and 4-point DFT for a sequence $x(n) = 2 \partial(n) \frac{3}{2} \partial(n-1)$.[8]
 - b) Obtain DTFT of left handed exponential signal $x(n) = a^{-n}u(-n-1)$. [8]
- Q5) a) Define ROC of Z transform. State significance of ROC. Derive the relationship between Z transform and fourier transform.[8]
 - b) Compare DIF FFT algorithm with DIT FFT algorithm. Draw basic butterfly structure for both. [10]

OR

Q6) a) Obtain the inverse z transform using residue method where

$$X(z) = \frac{1}{(z-1)(z-3)}.$$
 [8]

- b) Determine the Z-transform of the following: [10]
 - i) $x(n)=n(-1)^n u(n)$
 - ii) $x(n)=n^2u(n)$

SECTION - II

Q7) a) Find the difference equation satisfying the input and output of an LTI system.[8]

$$H(z) = \frac{(1+z^{-1})^2}{\left(1 - \frac{1}{2}z^{-1}\right)\left(1 + \frac{3}{4}z^{-1}\right)}.$$

b) Determine impulse response of a system:

$$y(n) = -3y(n-1) - 2y(n-2) + 2x(n) + x(n-1)$$
 [8]

OR

- **Q8)** a) Explain the method of simple geometric interpretation to obtain the frequency response of DT system. [8]
 - b) Determine H(z) and draw a pole zero plot for a system. [8]

$$y(n) + \frac{3}{4}y(n-1) + \frac{1}{8}y(n-2) = x(n) + x(n-1)$$

- **Q9)** a) Explain Gibb's phenomenon associated with FIR filter design. What are the desirable features of window function to improve the frequency response? [10]
 - b) Explain the design steps of FIR filter using rectangular window. State the advantages of windowing method. [8]

OR

- Q10)a) What are the different methods to design IIR filters? How stable analog filter is converted into stable digital filter? Explain the concept of frequency warping and prewarping?[10]
 - b) Design the digital IIR filter with a 3 dB bandwidth of 0.2π by using BLT method. The transfer function of $H(s) = \frac{\Omega c}{s + \Omega}$ where Ω_c is the 3 dB bandwidth of analog filter. [8]
- Q11)a) Explain the cascade form structure of FIR filter and realize the following system function for the same. [10]

$$H(z) = \left(1 + \frac{1}{2}z^{-1} + z^{-2}\right)\left(1 + \frac{1}{4}z^{-1} + z^{-2}\right).$$

b) Compare DSP processor and general purpose processors. [6]

OR

Q12)a) The transfer function of discrete time causal system is given by [10]

$$H(z) = \frac{1 - z^{-1}}{(1 - 0.5z^{-1})(1 + 0.3z^{-1})}$$

Draw cascade and parallel realization of IIR filter.

b) Draw a direct form - I IIR filter structure for:

[6]

H(z)=3+
$$\frac{4z}{(z-0.5)}$$
- $\frac{2}{(z-0.25)}$.

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