

[5154] - 198

B.E. (Information Technology)

EMBEDDED SYSTEMS

(2008 Course) (Semester - I) (Elective - II) (414444 A)

Time : 3 Hours]

[Max. Marks :100

Instructions to the candidates:

- 1) Answers to the two sections should be written in separate answer books.*
- 2) In section I attempt: Q.No.1 or Q.No.2, Q.No.3 or Q.No.4, Q.No.5 or Q.No.6.
In section II attempt: Q.No.7 or Q.No.8, Q.No.9 or Q.No.10, Q.No.11 or Q.No.12.*
- 3) Neat diagrams must be drawn wherever necessary.*
- 4) Figures to the right indicate full marks.*
- 5) Assume suitable data, if necessary.*

SECTION-I

- Q1)** a) What are the advantages of using ASIC & ASSP in embedded systems? Explain. [8]
- b) What are the criteria for selecting microprocessors or microcontrollers for an application? [8]

OR

- Q2)** a) What are the embedded systems? How they are different than general purpose systems? [6]
- b) What are the different components of an embedded system? [6]
- c) Differentiate between CISC and RISC. [4]
- Q3)** a) Describe the use of timers/counters and watchdog timers in Embedded system. [6]
- b) What are the techniques of power & energy management in a system?[6]
- c) What are the types of memory that can be integrated in a processor?[6]

OR

P.T.O.

- Q4)** a) How a designer selects EPROM, RAM and peripherals required for a robot arm control application? Explain. [8]
- b) What is the importance of clocking unit in embedded systems? How does it affect performance of an embedded system? [4]
- c) Explain the typical memory map for a small scale embedded application. [6]
- Q5)** a) What is the difference between serial & parallel I/O? Mention different standards used for both. [8]
- b) Describe SPI protocol in brief and the applications where it is preferred. [8]

OR

- Q6)** a) Explain different frames used for communication in CAN protocol. [8]
- b) How does host recognize the device insertion in USB protocol? Explain in detail. [8]

SECTION-II

- Q7)** a) What are the different phases of software development cycle for a typical embedded system? [8]
- b) What are the different debugging tools available for embedded system programming? [6]
- c) When do you use high level language instead of assembly language for embedded system programming? [4]

OR

- Q8)** a) Compare Java and C++ programming and their suitability for embedded systems. [6]
- b) What is cross compiler? Name one. How it is different than generic compiler? [6]
- c) With an example explain how stacks and queues are used to implement application functionality in embedded system software. [6]

- Q9) a)** What are the different characteristics of real time operating system? Give two example of RTOS. [6]
- b) With the help of neat diagram, explain cyclic scheduling model for RTOS. What is interrupt latency time for this scheduling model. [10]

OR

- Q10)a)** With the help of neat diagram, explain preemptive scheduling for RTOS.[8]
- b) Define and explain interrupt latency period. What is its significance in RTOS? [4]
- c) What is a Pipes? Give details. [4]
- Q11)a)** Differentiate Micro C/OS-II and Vx Works based on features and their area of application. [6]
- b) With the help of neat system block diagram, explain the system requirements and tasks for chocolate vending machine. [10]

OR

- Q12)a)** How tasks are managed in Micro C/OS-II? Explain in detail. [8]
- b) With help of neat diagram, explain synchronization of tasks and IPCs for smartcard application. [8]

EEE