Total No. of Questions: 10]		SEAT No. :
P2978	[5154]-532	[Total No. of Pages : 3

B.E. (Mechanical Engineering) CAD/CAM and Automation (2012 Course) (End Semester) (402042)

Time: 2½ Hours] [Max. Marks: 70

Instructions to the candidates:

- 1) Answer five questions.
- 2) Figures to the right indicate full marks.
- 3) Use of electronic calculator allowed.
- 4) Assume suitable data.
- **Q1)** A line is drawn with vertices A(4,4) B(15,10) has undergone following transformation in sequence. [10]
 - a) Rotation through 45° anticlockwise
 - b) Scaling by 1.5 units.
 - c) Reflection about x axis.

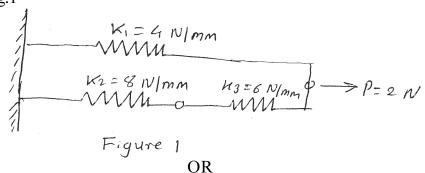
Find concatenated matrix and new co-ordinates of triangle.

OR

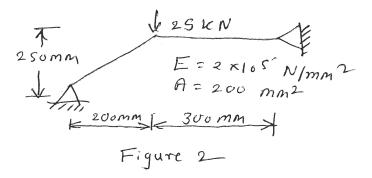
- **Q2)** a) Write equation of line having $P_1[3,5,8]$ and $P_2[6,4,3]$ and find tangent vectors and points on line at $\mu = 0.25, 0.5, 0.75$. [5]
 - b) Write short notes on Hermite cubic spline curve with neat sketch. [5]

Q3) a) Explain feature based modelling.

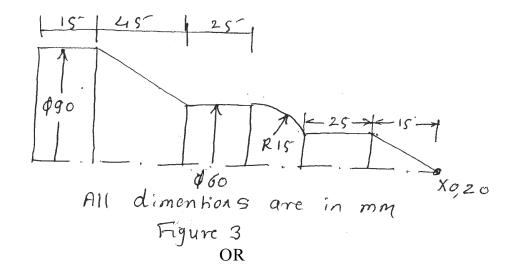
b) Find displacement and reaction force for cluster of springs as shown in fig.1 [6]

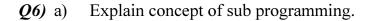


Q4) Truss element is as shown in figure 2. Determine, deflection, stresses and reaction force in element. [10]



- **Q5)** a) Explain canned cycle for parting and threading for turned components. [6]
 - b) Write CNC port program for roughing and finishing using canned cycle for turned components as shown in figure 3. Assume suitable data [12]

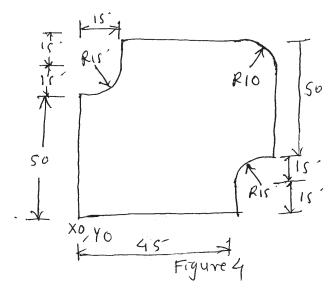




[6]

b) Write CNC program for the component shown in figure 4.

[12]



Q7) a) Explain basic steps in R.P. process.

[6]

b) Explain fused deposite manufacturing R.P. process.

[10]

OR

- **Q8)** a) Explain laminated object manufacturing (LOM) modelling method of R.P. [12]
 - b) Explain of R.P. Aerospace Industry.

[4]

Q9) a) Explain various joints used in robots with neat sketch.

[8]

b) Explain the vacuum gripper with neat sketch and its applications. [8]

OR

Q10)a) Explain Automation strategies.

[8]

b) Explain Group Technology layout and advantages over process layout. [8]

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