

[5354]-583

**B.E. (Electronics)**

**ADVANCED POWER ELECTRONICS**

**(2012 Pattern) (Theory)**

**Time : 2 ½ Hours]**

**[Max. Marks : 70**

**Instructions to the candidates :**

- 1) Answer Q1 or Q2, Q3 or Q4, Q5 or Q6, Q7 or Q8.
- 2) Neat diagrams must be drawn wherever necessary.
- 3) Figures to the right side indicate full marks.
- 4) Assume Suitable data if necessary.

**Q1) a)** Explain in detail with waveforms the effect of source impedance on performance of LCC. **[6]**

b) Explain following power factor improvement (any one) techniques for single phase converters with suitable waveforms and equations

- i) Extinction Angle Control (EAC)
- ii) Symmetrical Angle Control (SAC)
- iii) Pulse Width Modulation Control (PWM)

**[7]**

c) The input voltage of a cycloconverter is 120 V (rms) 60 Hz. The load resistance is  $5\Omega$  and the load inductance is  $L$  is 40mH. The frequency of the output voltage is 20 Hz. If the converters are operated as semi converters such that  $0 \leq \alpha \leq \pi$  and the delay angle is  $\alpha_p = 2\pi/3$ . Calculate **[7]**

- i) The rms value of the output voltage  $V_o$
- ii) The rms current of each of the thyristor  $I_g$  and the input power factor (PF).

**P.T.O.**

OR

- Q2)** a) Compare Circulating and non-Circulating current type dual converters. [6]  
b) A 3 phase dual converter is operated from a delta star connected transformer of 220 Volts, 50Hz supply, If the load resistance is  $10\Omega$ , the circulating inductance is 7.5mH and  $\alpha_1 = 50^\circ$ , Calculate Peak circulating current and current of converter - I [7]  
c) With the help of neat circuit diagram and waveforms explain the operation of single phase bridge Diode Clamped Multilevel inverter. State its features, advantages and disadvantages. [7]

**Q3)** What is braking? Explain Regenerative braking of DC machine. Mention its advantages and disadvantages. [6]

- a) A 15 HP 220 V, 2000 rpm separately excited DC motor controls load requiring a torque  $T_L = 45 \text{ N-m}$  at a speed of 1200 rpm. Field resistance  $R_f = 147 \Omega$ , armature resistance  $R_a = 0.25 \Omega$  and the voltage constant of the motor is  $K_v = 0.7302 \text{ V/A-rad/S}$ . The field voltage is 220V. The viscous friction and no load losses are negligible. Armature current can be assumed to be continuous and ripple free. Calculate back emf  $E_g$ , required armature voltage  $E_a$  and the rated armature current of the motor. [6]  
b) Calculate transfer function block diagram of DC motor. [4]

OR

- Q4)** a) Explain and draw the curve torque and power versus speed separately excited dc motor. [6]  
b) Draw and explain the power circuit of single phase semi-converter feeding a separately excited DC motor. Explain with typical waveforms, the operation in continuous and discontinuous armature current modes. [6]  
c) Compare converter fed and chopper fed drive. [4]

- Q5)** a) Explain variable square wave VSI Drives along with block diagram and application. [8]  
b) What is the need of vector control in Induction Motors? Briefly explain Vector control of induction motors. [10]

OR

- Q6)** a) Compare various speed control techniques of Induction motor on the basis of performance parameters. [8]
- b) With the help of suitable circuit diagram and waveforms explain the working of Variable frequency PWM VSI Drives. [10]
- Q7)** a) Compare variable reluctance motor with permanent magnet stepper motor. [8]
- b) Explain block diagram of volts/hertz control of synchronous motor drive along with the torque slip characteristics and the applications. [8]

OR

- Q8)** a) Explain with a diagram the construction, working and typical applications of Universal motor. [8]
- b) Explain the operation of a switched reluctance motor drive. [8]

▽▽▽▽