

Total No. of Questions : 10]

SEAT No. :

**P3056**

[Total No. of Pages : 3

**[5354] - 545**

**B.E. Mechanical**

**ROBOTICS (ELECTIVE - III)**

**(2012 Pattern) (Semester - II)**

**Time : 2½ Hours]**

**[Max. Marks : 70**

**Instructions to candidates:**

- 1) *Figures to the right indicate full marks.*
- 2) *Draw neat figures wherever necessary.*
- 3) *Use of scientific calculators is allowed.*

**Q1) a) State three laws of Robotics. [4]**

b) What is D-H parameter? Obtain an expression for D-H parameter matrix. [6]

OR

**Q2) a) What are Homogeneous Transformation & Homogeneous Transformation Matrix? [4]**

b) Write a short note on [6]

i) Algebraic Approach

ii) Geometric Approach

**Q3) a) Describe the four basic parameters used in DH notation algorithm [4]**

b) Explain with neat sketch static forces in manipulator. [6]

OR

**Q4) a) Explain properties of Jacobian matrix of a manipulator. [4]**

b) Explain with neat sketch linear and rotational velocities of rigid bodies. [6]

**P.T.O.**

**Q5) a)** Derive an equations of motion for serial manipulators using Lagrangian formulation [8]

b) Derive an equations of motion for parallel manipulators using Lagrangian formulation [8]

OR

**Q6) a)** A rotary arm of a manipulator is to rotate from  $20^\circ$  to  $80^\circ$  in 6 seconds. Determine coefficients of cubic polynomial to interpolate a smooth trajectory. Plot the position, velocity and acceleration variation against time [10]

b) What are the different tools used in simulations of robot? [6]

**Q7) a)** Explain independent joint of PID control. [8]

b) Explain in detail Trajectory planning of robot with its advantages? [8]

OR

**Q8) a)** Explain in detail force control of manipulators [8]

b) Fig. shows as error time graph. Sketch the PD controller o/p w.r.t. time. Assume  $k_p=5$ ,  $K_d=0.5$  &  $P_o=30\%$  i.e. controller o/p is 30% when error is zero. [8]

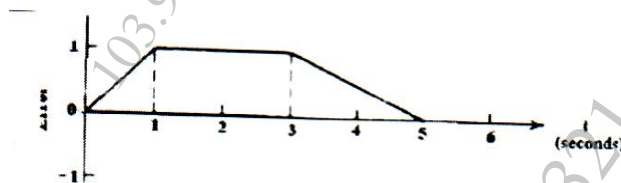


Figure 3

**Q9) a)** Explain Necessity & application of Artificial Intelligence for Robotics System. [8]

b) Explain the forward & backward search technique in problem solving for AI [10]

OR

- Q10)a)** Explain in detail Image Processing Techniques and Image Segmentation? **[12]**
- b) Write short note on linear Kalman Filter? **[6]**

