

Oct. 2018 In-sem T₁
Civi)
Engg. Maths II) U218-111(T1)
Scheme of Marking (2 pages)

Q-1]

a]

correct C.F. — 1 mark
correct value of Δ — 1 mark
correct values of u & V — 2 marks
correct ~~P~~ P.I. — 1 mark
correct last answer — 1 mark

b]

correct C.F. — 2 marks
correct P.I. — 2 marks
correct solution in terms of x — 2 marks

c]

correct C.F. — 1 mark
correct P.I. — 3 marks

Q-2]

a]

correct value of y (or x) — 3 marks
correct value of x (or y) — 3 marks

b]

C.F. — 2 marks
P.I. — 2 marks
correct answer in terms of x — 2 marks

ae-2] c] 1st correct solution - 2 marks
2nd independent solution - 2 marks

ae-3] a] correct values of
 k_1 — 1 mark
 k_2 — 1 mark
 k_3 — 1 mark
 k_4 — 1 mark
 k — 1 mark
 $y = y_0 + k$ - 1 mark

b] Gauss seidel correct formula
———— 1 mark

correct approximate answer - 3 marks

c] Fourier Sine Transform - 3 marks
Fourier integral representation - 1 mark

ae-4] a] correct values of k_1, k_2, k_3, k_4, k
———— 5 marks

correct value of y - 1 mark

b] Elimination of variables x, y, z &
~~1 mark~~ pivoting equations - 3 marks
correct answers of x, y, z - 1 mark

c] Inverse Fourier sine Transform - 3 marks

page 2/2 Fourier ~~has~~ value of $f(x)$ - 3 marks

Q-13 a) A.E. $D^2 + 4 = 0$ roots $D = \pm 2i$

C.F. $= C_1 \cos 2x + C_2 \sin 2x$ — 1 mark

$\Delta = \begin{vmatrix} \cos 2x & \sin 2x \\ -2 \sin 2x & 2 \cos 2x \end{vmatrix} = 2$ — 1 mark

P.I. $= Uy_1 + Vy_2 = U \cos 2x + V \sin 2x$

$U = - \int \frac{y_2 f(x)}{\Delta} dx = - \int \frac{\sin 2x \tan 2x}{2} dx$

$= - \frac{1}{2} \int \frac{\sin 2x}{\cos 2x} dx = - \frac{1}{2} \int \frac{1 - \cos 2x}{\cos 2x} dx$

$= - \frac{1}{2} \left\{ \int \sec 2x dx - \int \cos 2x dx \right\}$

$= - \frac{1}{2} \left\{ \frac{1}{2} \log(\sec 2x + \tan 2x) - \frac{1}{2} \sin 2x \right\}$

$U = - \frac{1}{4} \log(\sec 2x + \tan 2x) + \frac{1}{4} \sin 2x$ — 1 mark

$V = \int \frac{y_1 f(x)}{\Delta} dx = \int \frac{\cos 2x \tan 2x}{2} dx$

$= \frac{1}{2} \int \sin 2x dx = - \frac{1}{4} \cos 2x$ — 1 mark

P.I. $= Uy_1 + Vy_2$

$= \left[-\frac{1}{4} \log(\sec 2x + \tan 2x) + \frac{1}{4} \sin 2x \right] \cos 2x$
 $+ \left(-\frac{1}{4} \cos 2x \right) \sin 2x$

$P.I. = -\frac{1}{4} \log(\sec 2x + \tan 2x) \cos 2x$ — 1 mark

$$y = C.F. + P.I$$

$$y = C_1 \cos 2x + C_2 \sin 2x - \frac{1}{4} \log(\sec 2x + \tan 2x) \cos 2x$$

$$Q-1-b) \quad x^2 \frac{d^2 y}{dx^2} - 3x \frac{dy}{dx} + 5y = x^2 \sin \log x$$

$$\text{put } x = e^z, \quad D = \frac{d}{dz},$$

$$x \frac{dy}{dx} = Dy, \quad x^2 \frac{d^2 y}{dx^2} = D(D-1)$$

$$\therefore (D^2 - D - 3D + 5)y = (e^z)^2 \sin \log e^z$$

$$(D^2 - 4D + 5)y = e^{2z} \sin z$$

$$A.E. \quad D^2 - 4D + 5 = 0$$

$$D = 2 \pm i$$

$$C.F. = e^{2z} [C_1 \cos z + C_2 \sin z]$$

2 marks

$$P.I. = \frac{1}{D^2 - 4D + 5} e^{2z} \sin z$$

$$= e^{2z} \frac{1}{D^2 + 1} \sin z = e^{2z} \frac{z}{2D} \sin z$$

$$P.I. = -\frac{e^{2z}}{2} z \cos z$$

2 marks

$$y = C.F. + P.I. = e^{2z} (C_1 \cos z + C_2 \sin z) - \frac{ze^{2z}}{2} \cos z$$

$$z = \log x$$

$$y = x^2 [C_1 \cos \log x + C_2 \sin \log x] - \frac{1}{2} x^2 \log x \cos \log x$$

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2 marks

$$Q-1 \quad c) (D^2 - 4D + 4)y = x e^{2x} \sin 2x$$

$$C.F. = (C_1 + C_2 x) e^{2x} \quad \text{--- 1 mark}$$

$$P.I. = \frac{1}{D^2 - 4D + 4} e^{2x} x \sin 2x$$

$$= e^{2x} \frac{1}{D^2} x \sin 2x$$

$$= e^{2x} \left[x - \frac{2D}{D^2} \right] \frac{1}{D^2} \sin 2x$$

$$= e^{2x} \left[x - \frac{2}{D} \right] \frac{1}{-4} \sin 2x$$

$$= -\frac{1}{4} e^{2x} \left[x \sin 2x - 2 \frac{1}{D} \sin 2x \right]$$

$$= -\frac{1}{4} e^{2x} [x \sin 2x + \cos 2x]$$

$$y = C.F. + P.I.$$

--- 2 marks

$$y = (C_1 + C_2 x) e^{2x} - \frac{1}{4} e^{2x} [x \sin 2x + \cos 2x]$$

1 mark

Q-2) a)

$$\frac{dx}{dt} - wy = a \cos pt \quad \text{--- (1)}$$

$$\frac{dy}{dt} + wx = a \sin pt \quad \text{--- (2)}$$

$$\Rightarrow D x - w y = a \cos pt \quad \text{--- (1)}$$

$$D w x + D y = a \sin pt \quad \text{--- (2)}$$

$$D(1) \Rightarrow D^2 x - \omega D y = a(-p \sin pt)$$

$$+ \omega(2) \Rightarrow \omega^2 x + \omega D y = a \omega \sin pt$$

$$(D^2 + \omega^2)x = a(-p + \omega) \sin pt$$

$$(D^2 + \omega^2)x = a(\omega - p) \sin pt \quad \text{mark} \quad \text{--- (3)}$$

$$x_c = c_1 \cos \omega t + c_2 \sin \omega t$$

$$x_p = \frac{1}{D^2 + \omega^2} a(\omega - p) \sin pt$$

$$= \frac{a(\omega - p)}{-p^2 + \omega^2} \sin pt$$

$$= \frac{a(\omega - p)}{(\omega + p)(\omega - p)} \sin pt$$

$$x = x_c + x_p$$

$$x = c_1 \cos \omega t + c_2 \sin \omega t + \frac{a}{\omega + p} \sin pt$$

--- 3 marks

from eqn (1)

$$\omega y = \frac{dx}{dt} - a \cos pt$$

$$y = \frac{1}{\omega} \left[\frac{dx}{dt} - a \cos pt \right]$$

$$y = c_2 \cos \omega t - c_1 \sin \omega t - \frac{a}{p + \omega} \cos pt$$

--- 2 marks

a-2 b}

$$(3x+2)^2 \frac{dy}{dx} + 3(3x+2) \frac{dy}{dx} - 36y = 3x^2 + 4x + 1$$

$$\text{put } 3x+2 = e^z$$

$$x = \frac{1}{3} [e^z - 2]$$

$$(3x+2) \frac{dy}{dx} = 3y$$

$$(3x+2)^2 \frac{d^2y}{dx^2} = 9D^2y - 9Dy$$

$$\therefore \{D^2 - 9D + 3(3D) - 36\}y$$

$$= 3\left[\frac{1}{3} e^{2z} - 1\right]^2 + 4\left[\frac{1}{3}(e^z - 2)\right] + 1$$

$$(D^2 - 4)y = \frac{1}{27} [e^{2z} - 1]$$

$$C.F. = C_1 e^{2z} + C_2 e^{-2z} \quad \text{--- 2 marks}$$

$$P.I. = \frac{1}{27} \left[\frac{1}{D^2 - 4} e^{2z} - \frac{1}{D^2 - 4} 1 \right]$$

$$= \frac{1}{27} \left[\frac{z}{2D} e^{2z} - \frac{1}{6-4} e^{0z} \right]$$

$$P.I. = \frac{1}{108} [ze^{2z} + 1] \quad \text{--- 3 marks}$$

$$y = C.F. + P.I.$$

$$y = (3x+2)^2$$

$$y = c_1 e^{2z} + c_2 e^{-2z} + \frac{1}{\log} [z e^{2z} + 1]$$

$$= c_1 (3x+z)^2 + \frac{c_2}{(3x+z)^2} + \frac{1}{\log} \left[\frac{1}{(3x+z)^2} \log \right]$$

$$+ \frac{1}{\log} [(3x+z)^2 \log(3x+z) + 1]$$

_____ 1 mark

Q-2 c) $\frac{dz}{3z-4y} = \frac{dy}{4x-2z} = \frac{dx}{2y-3x}$

select multipliers x, y, z

each ratio = $\frac{x dx + y dy + z dz}{0}$

$\Rightarrow x dx + y dy + z dz = 0$

integrating

$\boxed{x^2 + y^2 + z^2 = c_1^2}$ — 2 marks

choose multipliers $2, 3, 4$ then

each ratio = $\frac{2 dx + 3 dy + 4 dz}{0}$

$\Rightarrow 2 dx + 3 dy + 4 dz = 0$

int $\Rightarrow \boxed{2x + 3y + 4z = c_2}$ — 2 mark

Q-3 a)

$$\frac{dy}{dx} = xy + y^2$$

$$x_0 = 0, y_0 = 1, h = 0.1$$

$$f(x, y) = xy + y^2$$

$$K_1 = h f(x_0, y_0) = 0.1 [0 + 1^2] = 0.1$$

$$K_2 = h f\left(x_0 + \frac{h}{2}, y_0 + \frac{K_1}{2}\right) \\ = 0.1 [f(0.05, 1.05)] = 0.1155$$

$$K_3 = h f\left(x_0 + \frac{h}{2}, y_0 + \frac{K_2}{2}\right) \\ = 0.1 f(0.05, 1.0577) = 0.1172$$

$$K_4 = h f(x_0 + h, y_0 + K_3) \\ = 0.1 f(0.1, 1.1172) = 0.13598$$

$$K = \frac{1}{6} [K_1 + 2K_2 + 2K_3 + K_4] = 0.11687$$

_____ 5 marks

$$y_1 = y_0 + K = 1 + 0.11687$$

$$y_1 = y(0.1) = 1.11687$$

_____ 1 mark

a-3-b}

Rearrange eqns as

$$27x + 6y - z = 85$$

$$6x + 15y + 2z = 72$$

$$x + y + 54z = 110$$

$$x = \frac{1}{27} [85 - 6y + z]$$

$$y = \frac{1}{15} [72 - 6x - 2z]$$

$$z = \frac{1}{54} [110 - x - y]$$

1 mark

Let initial approximation

$$x^0 = 0, y^0 = 0, z^0 = 0$$

By Gauss Seidel method
1st iteration

$$x^1 = \frac{1}{27} [85 - 0 + 0] = 3.14$$

$$y^1 = \frac{1}{15} [72 - 6(3.14) - 2(0)] = 3.541$$

$$z^1 = \frac{1}{54} [110 - 3.14 - 3.541] = 1.913$$

2nd iteration

$$x^{(2)} = 2.432, y^{(2)} = 3.572, z^{(2)} = 1.926$$

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3 marks

Q-3-c]

claim: $\int_0^{\infty} \frac{1-\cos \pi \lambda}{\lambda} \sin \lambda x d\lambda = \begin{cases} \frac{\pi}{2} & 0 < x < \pi \\ 0 & , x \geq \pi \end{cases}$

$$f(x) = \begin{cases} \frac{\pi}{2} & 0 < x < \pi \\ 0 & , x \geq \pi \end{cases}$$

As this integral contain $\sin \lambda x$
 $\therefore$ we find Fourier sine Transform

$$\begin{aligned} F_s(\lambda) &= \int_0^{\infty} f(x) \sin \lambda x dx \\ &= \int_0^{\pi} \frac{\pi}{2} \sin \lambda x dx + \int_{\pi}^{\infty} 0 \\ &= -\frac{\pi}{2} \left[\frac{\cos \lambda x}{\lambda} \right]_0^{\pi} \\ &= -\frac{\pi}{2\lambda} [\cos \lambda \pi - 1] \end{aligned}$$

$$\boxed{F_s(\lambda) = \frac{\pi}{2\lambda} [1 - \cos \lambda \pi]} \text{---3 marks}$$

By Fourier sine integral representation

$$f(x) = \frac{2}{\pi} \int_0^{\infty} F_s(\lambda) \sin \lambda x d\lambda$$

$$\Rightarrow \frac{2}{\pi} \int_0^{\infty} \frac{\pi}{2\lambda} (1 - \cos \lambda \pi) \sin \lambda x d\lambda = \begin{cases} \frac{\pi}{2} & , 0 < x < \pi \\ 0 & , x \geq \pi \end{cases}$$

———— 1 mark, 1/2/2

$$Q-4) a) \frac{dy}{dx} = \frac{y^2 - x^2}{y^2 + x^2}, \quad x_0 = 0, y_0 = 1$$

$$h = 0.2$$

$$f(x, y) = \frac{y^2 - x^2}{y^2 + x^2}$$

$$K_1 = h f(x_0, y_0) = 0.2 f(0, 1) = 0.2$$

$$K_2 = h f(x_0 + \frac{h}{2}, y_0 + \frac{K_1}{2}) = 0.2 f(0.1, 1.1) = 0.19672$$

$$K_2 = 0.19672$$

$$K_3 = h f(x_0 + \frac{h}{2}, y_0 + \frac{K_2}{2}) = 0.2 f(0.1, 1.09836) = 0.1967$$

$$K_4 = h f(x_0 + h, y_0 + K_3) = 0.2 f(0.2, 1.1967)$$

$$K_4 = 0.1891$$

$$K = \frac{1}{6} [K_1 + 2K_2 + 2K_3 + K_4] = 0.19599$$

————— 5 marks

$$y_1 = y(0.2) = y_0 + K = 1 + 0.19599$$

$$y_1 = 1.19599 \quad \text{————— 1 mark.}$$

Q-4) b) Gauss Elimination method

$$x + y + z = 9 \quad \text{--- (1)}$$

$$2x - 3y + 4z = 13 \quad \text{--- (2)}$$

$$3x + 4y + 5z = 40 \quad \text{--- (3)}$$

page 10/12 ^{1st} pivot = 1

a-k-b) eliminating z from last two eqⁿs

$$-5x + 2z = -5 \quad \text{--- (4)}$$

$$y + 2z = 13 \quad \text{--- (5)}$$

2nd

$$\text{pivot} = -5$$

pivoting eqⁿ (4)

$$x - \frac{2}{5}z = 1 \quad \text{--- (6)}$$

eliminating y from (5)

$$\frac{12z}{5} = 12$$

$$3rd \quad \text{pivot} = 12/5$$

~~pivoting~~ dividing last eqⁿ by $12/5$

$$z = 5$$

$$\Rightarrow y = 3$$

$$\Rightarrow x = 1$$

$\therefore$ solⁿ

$$x = 1, \quad y = 3, \quad z = 5.$$

mark

Q-4-b) Alternative way
by using Augment matrix
matrix $[A:B]$
full marks.

Q-4 c)

~~f(x)~~ let $F_S(\lambda) = \begin{cases} 1-\lambda, & 0 \leq \lambda \leq 1 \\ 0, & \lambda > 1 \end{cases}$

$$f(x) = \frac{2}{\pi} \int_0^{\infty} F_S(\lambda) \sin \lambda x d\lambda$$

$$= \frac{2}{\pi} \int_0^1 (1-\lambda) \sin \lambda x d\lambda + \int_1^{\infty} 0$$

$$= \frac{2}{\pi} \left\{ (1-\lambda) \left[\frac{\cos \lambda x}{x} \right] - [-1] \left[-\frac{\sin \lambda x}{x^2} \right] \right\}_0^1$$

$$f(x) = \frac{2}{\pi} \left\{ -(1-\lambda) \frac{\cos \lambda x}{x} - \frac{\sin \lambda x}{x^2} \right\}_0^1$$

$$= \frac{2}{\pi} \left\{ \left[0 - \frac{\sin x}{x^2} \right] - \left[-(1-0) \frac{1}{x} - \right] \right\}$$

$$f(x) = \frac{2}{\pi} \left[\frac{1}{x} - \frac{\sin x}{x^2} \right]$$