

Total No. of Questions – [03]

Total No. of Printed Pages: [02]

PRN No.	
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Paper Code	V223-261 (ESE)
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MAY 2023 ENDSEM EXAM
S.Y. B. TECH.(MECHANICAL) (SEMESTER - II)
COURSE NAME: INSTRUMENTATION AND CONTROL
COURSE CODE: MEUA22201
(PATTERN 2020)

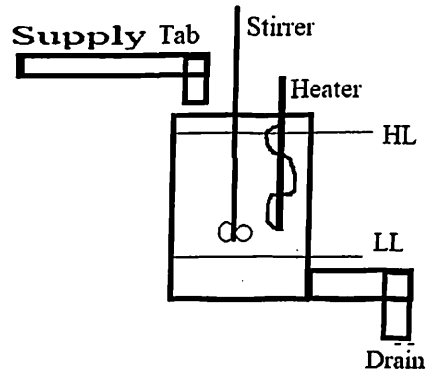
Time: [1 Hr]

[Max. Marks: 30]

Instructions to candidates:

- 1) Figures to the right indicate full marks.
- 2) 'a' part of every question is compulsory
- 3) Use of scientific calculator is allowed
- 4) Use suitable data where ever required

Question No.	Question Description	Marks	CO mapped	Blooms Taxonomy Level
Q.1	a) Explain different buses of communication channel?	[4]	[4]	[2]
	b) Build the ladder logic for a simple traffic light controller for following sequence of operation, Step 1 : Turn Green on for 25 seconds Step 2 : Turn Yellow on for 7 seconds. Step 3 : Red on for 30 seconds. Step 4 : Sequence repeats thereafter.	[6]	[4]	[3]
	OR c) Build the ladder diagram for Switch 'ON' supply Tab to fill the tank till 'HL'. At 'HL' Supply Tab will Off and Heater and Stirrer will start for 5 min. After 5 min Heater and stirrer will off and Drain Valve will ON till "LL" and followed by repeat the same cycle	[6]	[4]	[3]



	<p>a) Define the following terms in time domain analysis</p> <p>1) Settling time?</p> <p>2) Delay time?</p> <p>b) Relationship of PID controller in series with its out- put explain with suitable Diagram.</p> <p style="text-align: center;">OR</p> <p>c) Compare the derivation for proportional and derivative Controller draw the diagram showing action of this controller.</p>	[4]	[5]	[1]
		[6]	[5]	[4]
		[6]	[5]	[4]
Q.3	<p>a) Compare Hydraulic and Pneumatic system,</p> <p>b) Examine the Damping of system by solving</p> $s^2 + 8s + 12 = 0$ <p>and tell about the value of Damping factor, natural frequency, settling time</p> <p style="text-align: center;">OR</p> <p>c) Examine the stability of the system by solving the array with Routh–Hurwitz stability criteria $3S^4+5S^3+10S^2+6S+12=0$ and state about stability of system</p>	[4]	[6]	[2]
		[6]	[6]	[4]
		[6]	[6]	[4]